



Air Gripper with lightness and high power!

Our original technic Patent applied for

Parallel type Square Gripper: CH91B

Cut the weight by half! And FWR by half!





*1 Force-weight ratio : actual weight per grip force 1N



not in use of copper and aluminium parts at all

Rise Force-weight Ratio and improve production efficiency!!

Broaden the capable for robot's transport

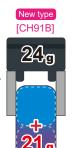
The weight of air gripper Old type [CH91A] [CH91B] attached to the machine's tip is Half weight of old type



SO...







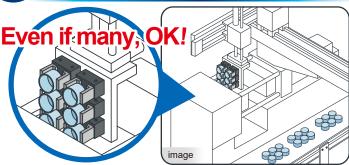


CH91B is so light and move swiftly. If more accurancy, less time will be taken to next movement.

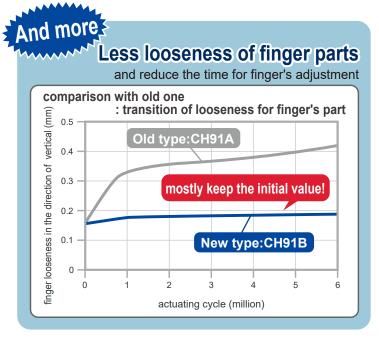


Shorten the takt time!

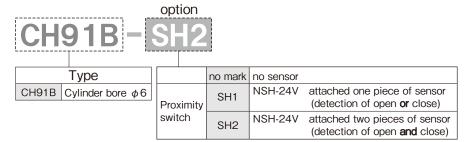
Enable to grip more works



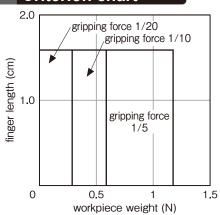
You can use more air grippers by reducing the total gripper's weight significately that is attached to the machine's tip.



Standard Model



Criterion chart

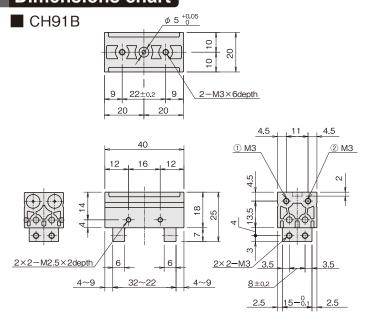


Specification

Mandain na an ail a		Ellamont of
Working media		Filtered air
Operating pressure (P)	MPa{kgf/cm²}	0.3~0.7{3~7.1}
Ambient temperature	(℃)	5~60
Lubrication		Normally not required
		(But if necessary, use 1st sort of turbine oil equivalent of ISO VG32)
Repetitive accuracy	(mm)	Initial value : ± 0.1 , At 2 million cycles : ± 0.2
Cylinder bore	(mm)	6
Stroke	(mm)	10
Exhaust volume	(cc)	0.16
Max. cycle per minute *1		90
Finger's movement		Double acting
Gripping force: Close,Open *2	(N)	18 x (P-0.18)
		P:operating pressure(MPa)
Weight	(g)	24
Max. length of attachment from finger end *1 (cm)		1.6
Max. weight of one attachment *1	(g)	15

^{*1} Variable by the working condition. *2 1N≒0.102kgf

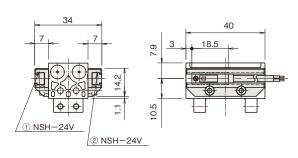
Dimensions chart



option

sensor detected for finger's open and close (Reed switch)

1	Air port (close)
2	Air port (open)



*3 Please connect the tubing to air port (close) sensor, because SH1(NSH-24V) is attached to air port (open) .

NKE株式会社 [旧社名(株)中村機器エンジニアリング]

NKE Corporation

◆Head office

366-1, Hishikawa-cho, Hazukashi, Fushimi-ku, Kyoto 612-8487, Japan Tel : 075-924-3293

Fax: 075-924-3290

- ◆URL=https://www.nke.co.jp
- ◆E-mail:promotion@nke.co.jp
- For technical questions, please contact us by E-mail at promotion@nke.co.jp>.
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